

Damper actuator for operating air control dampers in ventilation and air-conditioning systems for building services installations

- Torque 4 Nm
- Nominal voltage AC/DC 24 V
- Control Open/close (not made for 3-point applications)
- Running time 2.5 s



Technical data				
Electrical data	Nominal voltage		AC 24 V, 50/60 Hz / DC 24 V	
	Nominal voltage range		AC 19.2 28.8 V / DC 21.6 28.8 V	
	Power consumption	In operation	13 W @ nominal torque	
		At rest	1.5 W	
		For wire sizing	23 VA (I max. 20 A @ 5 ms)	
	Connection		Cable 1 m, 3 x 0.75 mm <sup>2</sup>	
Functional data	Torque (nominal torque	ue)	Min. 4 Nm @ nominal voltage	
	Direction of rotation		Reversible with switch 0 r or 1	
	Manual override		Gearing latch disengaged with push-button, can be locked	
	Angle of rotation		Max. 95°	
	Running time		2.5 s / 90° < ✓	
	Automatic adjustment of operating range and measuring signal U to match the mechanical angle of rotation		Manual triggering of the adaption by pressing the «Adaption» button	
	Sound power level		52 dB (A)	
	Position indication		Mechanical, pluggable	
	Negative torque	Δ	≤50% from nominal torque (Caution: can only be used with restrictions. Please contact your Belimo representative.)	
Safety	Protection class		III Safety extra-low voltage	
•	Degree of protection		IP54 in any mounting position, UL/NEMA 2	
	EMC		CE according to 2004/108/EC	
	Certification		cULus according to UL 60730-1A and UL 60730-2-14 and CAN/CSA E60730-1:02 Certified to IEC/EN 60730-1 and IEC/EN 60730-2-14	
	Mode of operation		Type 1 (EN 60730-1)	
	Rated impulse voltag	e	0.8 kV (EN 60730-1)	
	Control pollution degr		3 (EN 60730-1)	
	Ambient temperature		−30 +40 °C (no restrictions)	
		A	+40 +50°C (Caution: can only be used with restrictions. Please contact your Belimo representative.)	
	Non-operating tempe	rature	−40 +80°C	
	Ambient humidity		95% RH, non condensing (EN 60730-1)	
	Maintenance		Maintenance-free	
Dimensions / Weight	Dimensions		See «Dimensions» on page 3	
	Weight		Approx. 850 g	



#### Safety notes



- This actuator is not allowed to be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- It may only be installed by suitably trained personnel.
   All applicable legal or institutional installation regulations must be complied with.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- · The cable must not be removed from the device.
- Self adaptation is necessary when the system is commissioned and after each adjustment of the angle (press the adaptation pushbutton)
- When calculating the required torque, the specifications supplied by the damper manufacturers (cross section, design, installation site), and the air flow conditions must be observed.
- The device contains electrical and electronic components and is not allowed to be disposed
  of as household refuse. All locally valid regulations and requirements must be observed.

#### **Product features**

Simple direct mounting

Simple direct mounting on the damper spindle with a universal spindle clamp, supplied with an anti-rotation strap to prevent the actuator from rotating.

Manual override

Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked).

Adjustable angle of rotation

Adjustable angle of rotation with mechanical end stops.

High functional reliability

The actuator is overload-proof, requires no limit switches and automatically stops when the end stop is reached.

Home position

When the supply voltage is switched on for the first time, i.e. at commissioning or after pressing the "gear disengagement" switch, the actuator moves to the home position.

Pos. Direction of rotation switch	Home position		
0 Y = 0 F	ccw 🚩	Left stop	
Y = 0	Cw	Right stop	

The actuator then moves into the position defined by the control signal.

#### **Accessories**

	Description	Data sheet
sories	Auxiliary switch SA	SA
	Feedback potentiometer PA	PA
sories	Various accessories (clamps, shaft extensions etc.)	Z-NMA

## **Electrical installation**

#### Wiring diagrams

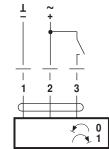
**Electrical access** 

Mechanical access

# Note

Connect via safety isolation transformer.

Other actuators can be connected in parallel.
 Note the performance data.



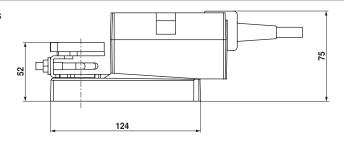
**Direction of rotation** 

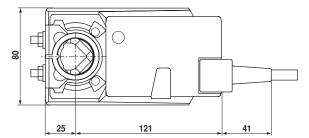




#### **Dimensions [mm]**

#### **Dimensional drawings**

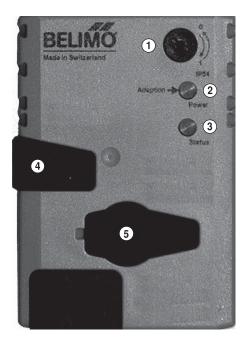




Damper spindle	Length	<u>OĪ</u>		<b>♦</b> Ţ
-	≥40	8 26.7	≥8	≤26.7
*	≥20	8 20	≥8	≤20

<sup>\*</sup> Option (accessory K-NA)

# Operating controls and indicators



#### 1 Direction of rotation switch

Switching over: Direction of rotation changes

# 2 Push-button and green LED display

Off: No voltage supply or fault

On: In operation

Press button: Switches on angle of rotation adaptation followed by standard operation

# 3 Push-button and yellow LED display

Off: Standard operation

On: Adaptation or synchronising process active

Press button: No function

# 4 Gear disengagement switch

Press button: Gear disengaged, motor stops, manual override possible

Release button: Gear engaged, synchronisation starts, followed by standard operation

#### Check voltage supply connection

a) ② Off and ③ On Check the supply connections.

) ② Blinking and ③ Blinking ☐ Possibly ± and ∓ are swapped over.

#### (5) No function



Modulating damper actuator for operating air control dampers in ventilation and air-conditioning systems for building services installations

- Torque 4 Nm
- Nominal voltage AC/DC 24 V
- Control: modulating DC 2(0) ... 10 V
- Position feedback DC 2 ... 10 V
- Running time 2.5 s



Technical data					
Electrical data	Nominal voltage		AC 24 V, 50/60 Hz / DC 24 V		
	Nominal voltage range		AC 19.2 28.8 V / DC 21.6 28.8 V		
	Power consumption In operation		13 W @ nominal torque		
	At rest		1.5 W		
	For wire sizing		23 VA (I max. 20 A @ 5 ms)		
	Connection		Cable 1 m, 4 x 0.75 mm <sup>2</sup> Min. 4 Nm @ nominal voltage  DC 2(0) 10 V, input impedance 100 kΩ  DC 2 10 V, max. 0.5 mA		
Functional data	Torque (nominal torque)				
	Control signal				
	Feedback signal				
	Position accuracy		±5%		
	Direction of rotation		Reversible with switch 0 / 1		
	Direction of motion at Y = 0 V		At switch position 0 🖍 resp. 1 🥕		
	Manual override		Gearing latch disengaged with push-button, can be locked		
	Angle of rotation		Max. 95°		
	Running time		2.5 s / 90°⊲		
	Automatic adjustment of operating range	е	Manual trianguing of the adentation by oversion the		
	and measuring signal U to match the mechanical angle of rotation		Manual triggering of the adaptation by pressing the «Adaptation» button		
	Override control		MAX (maximum position) = 100% MIN (minimum position) = 0%		
			ZS (intermediate position, only AC) = 50%		
	Sound power level		52 dB (A)		
	Position indication		Mechanical, pluggable		
	Negative torque	Δ	≤50% from nominal torque (Caution: can only be used with restrictions. Please contact your Belimo representative.)		
Safety	Protection class		III Safety extra-low voltage		
Culoty	Degree of protection		IP54 in any mounting position, UL/NEMA 2		
	EMC		CE according to 2004/108/EC		
	Mode of operation		Type 1 (EN 60730-1)		
	Certification		cULus according to UL 60730-1A and UL 60730-2-14 and CAN/CSA E60730-1:02		
	Date d francisco code		Certified to IEC/EN 60730-1 and IEC/EN 60730-2-14		
	Rated impulse voltage		0.8 kV (EN 60730-1)		
	Control pollution degree		3 (EN 60730-1)		
	Ambient temperature		-30 +40 °C (no restrictions)		
		A	+40 +50°C (Caution: can only be used with restrictions. Please contact your Belimo representative.)		
	Non-operating temperature		-40 +80°C		
	Ambient humidity		95% RH, non condensing (EN 60730-1)		
	Maintenance		Maintenance-free		
Dimensions / Weight	Maintenance Dimensions		Maintenance-free  See «Dimensions» on page 5		



#### Safety notes



- This actuator is not allowed to be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- It may only be installed by suitably trained personnel. Any legal regulations or regulations issued by authorities must be observed during assembly.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- · The cable must not be removed from the device.
- Self adaptation is necessary when the system is commissioned and after each adjustment of the angle (press the adaptation pushbutton)
- When calculating the required torque, the specifications supplied by the damper manufacturers (cross section, design, installation site), and the air flow conditions must be observed.
- The device contains electrical and electronic components and is not allowed to be disposed
  of as household refuse. All locally valid regulations and requirements must be observed.

#### **Product features**

Mode of operation

The drive is actuated with a standard modulating signal DC  $2(0) \dots 10 \text{ V}$  and travels to the position defined by the control signal. The measuring voltage U serves for the electrical display of the damper position  $0 \dots 100\%$  and as slave control signal for other actuators.

Simple direct mounting

Simple direct mounting on the damper spindle with a universal spindle clamp, supplied with an anti-rotation strap to prevent the actuator from rotating.

Manual override

Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked).

Adjustable angle of rotation

Adjustable angle of rotation with mechanical end stops.

High functional reliability

The actuator is overload-proof, requires no limit switches and automatically stops when the end stop is reached.

Home position

When the supply voltage is switched on for the first time, i.e. at commissioning or after pressing the "gear disengagement" switch, the actuator moves to the home position.

Pos. Direction of rotation switch		Home position			
	Y = 0	ccw 🚩	Left stop		
1)	Y = 0	Cw	Right stop		

The actuator then moves into the position defined by the control signal.

#### **Accessories**

	Description	Data sheet
Electrical accessories	Auxiliary switch SA	SA
	Feedback potentiometer PA	PA
	Positioner SG24	SG24
	Range controller SBG24	SBG24
	Room temperature controller CR24	CR24
	Digital position indication ZAD24	ZAD24
Mechanical accessories	Various accessories (clamps, shaft extensions etc.)	Z-NMA

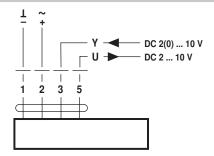


# **Electrical installation**

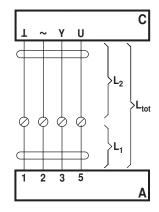
### Wiring diagram

#### Note

- Connect via safety isolation transformer.
- Other actuators can be connected in parallel. Note the performance data.



#### Cable lengths



= Actuator С = Control unit

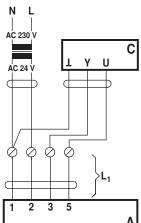
 $L_1$  = Belimo connecting cable, 1 m (4 x 0.75 mm<sup>2</sup>)

L<sub>2</sub> = Customer cable
L<sub>tot</sub> = Maximum cable length

### Note

When several actuators are connected in parallel, the maximum cable length must be divided by the number of actuators.

Cross section	max. cable length		Example for DC
L <sub>2</sub>	$L_{tot} = L_1 + L_2$		
1/~	AC	DC	
0.75 mm <sup>2</sup>	≤ 30 m	≤ 5 m	1 m (L <sub>1</sub> ) + 4 m (L <sub>2</sub> )
1.00 mm <sup>2</sup>	≤ 40 m	≤ 8 m	1 m (L <sub>1</sub> ) + 7 m (L <sub>2</sub> )
1.50 mm <sup>2</sup>	≤ 70 m	≤ 12 m	1 m (L <sub>1</sub> ) + 11 m (L <sub>2</sub> )
2.50 mm <sup>2</sup>	≤ 100 m	≤ 20 m	1 m (L <sub>1</sub> ) + 19 m (L <sub>2</sub> )



# С L<sub>1</sub> = Belimo connecting cable, 1 m (4 x 0.75 mm<sup>2</sup>)

= Actuator

Control unit

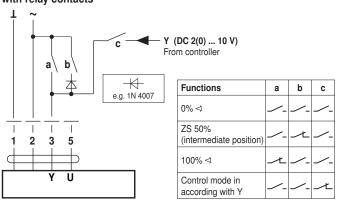
#### Note

There are no special restrictions on installation if the supply and data cable are routed separately

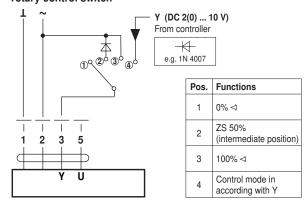


#### Functions with basic values

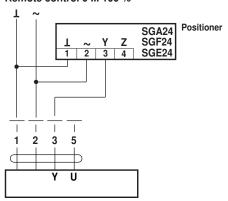
#### Override control with AC 24 V with relay contacts



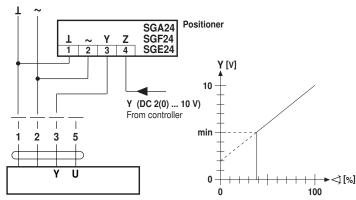
#### Override control with AC 24 V with rotary control switch



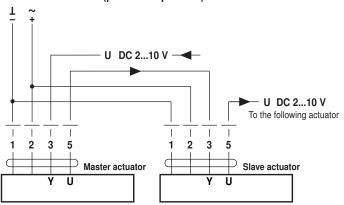
#### Remote control 0 ... 100 %



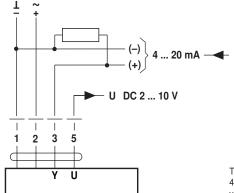
#### Minimum limit



#### Master/Slave control (position-dependent)

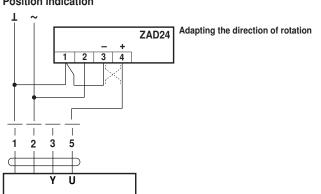


Control with 4 ... 20 mA via external resistance

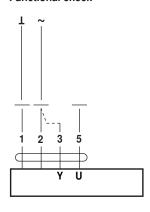


The 500  $\Omega$  resistor converts the 4 ... 20 mA current signal into a voltage signal DC 2 ... 10 V

#### **Position indication**



# **Functional check**



# Procedure

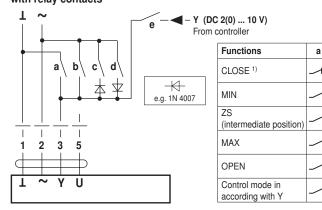
- Apply AC 24 V to connection 1 and 2
- Disconnect connection 3:
- For direction of rotation 0:
- Actuator turns in the direction of 🗲
- For direction of rotation 1:
- Actuator turns in the direction of ( • Short circuit connections 2 and 3:
- Actuator runs in the opposite direction

b c d e

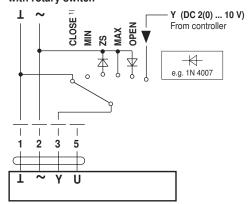


# Functions for actuators with specific parameters

# Override control and limiting with AC 24 V with relay contacts

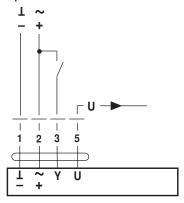


# Override control and limiting with AC 24 V with rotary switch



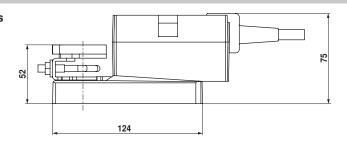
<sup>1)</sup> Caution! This function is only guaranteed if the start point of the operating range is defined as min. 0.6 V.

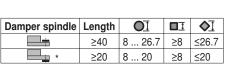
#### Open-close control



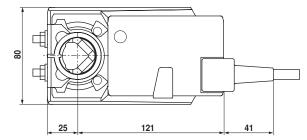
# Dimensions [mm]

# **Dimensional drawings**











# Operating controls and indicators



1 Direction of rotation switch

Switching over: Direction of rotation changes

2 Push-button and green LED display

Off: No voltage supply or fault

On: In operation

Press button: Switches on angle of rotation adaptation followed by standard operation

3 Push-button and yellow LED display

Off: Standard operation

On: Adaptation or synchronising process active

Press button: No function

4 Gear disengagement switch

Press button: Gear disengaged, motor stops, manual override possible

Release button: Gear engaged, synchronisation starts, followed by standard operation

Check voltage supply connection

a) ② Off and ③ On
 b) ② Blinking and ③ Blinking

Check the supply connections.
Possibly ± and ∓ are swapped over.

(5) No function